

Reyrolle Protection Devices

# 7SR11 and 7SR12 Argus Overcurrent Relays

Answers for energy



# 7SR11 and 7SR12 Argus

**Overcurrent Relays** 



# Description

The 7SR11 & 7SR12 are overcurrent protection relays developed to enhance the Argus family of products by providing a familiar product using the latest generation of hardware technology.

The 7SR11 overcurrent and earth fault relays and the 7SR12 directional relays are available in single and four pole variants.

Housed in a 4U high, size E4 case, these relays provide protection, monitoring, instrumentation and metering with integrated input and output logic, data logging & fault reports. Communication access to the relay functionality is via a front USB port for local PC connection or rear electrical RS485 port for remote connection.

# **Function Overview**

### Protection

1 locection	
37	Undercurrent
46BC	Broken Conductor / Load Unbalance
46NPS	Negative Phase Sequence Overcurrent
49	Thermal Overload
50	Instantaneous Overcurrent
50G/N/SEF	Instantaneous Earth Fault
50BF	Circuit Breaker Fail
51	Time Delayed Overcurrent
51G/N/SEF	Time Delayed Measured/Derived/Sensitive Earth
	Fault
64H	High Impedance REF
27/59	Under/Over Voltage
47	Negative Phase Sequence Voltage
51V	Voltage Controlled Overcurrent
59N	Neutral Voltage Displacement
67/50	Directional Instantaneous Overcurrent
67/50G/N	Directional Instantaneous Earth Fault
67/51	Directional Time Delayed Overcurrent
67/51G/N	Directional Time Delayed Earth Fault
81HBL2	Inrush Detector
81	Under/Over Frequency
	Line Check/Switch onto Fault

#### Supervision

60CTS CT Supervision

# 74T/CCS Trip & Close Circuit Supervision 60VTS VT Supervision

- 79Auto Reclose86Lockout
- CB Control

# Features

Cold Load Settings Four Settings Groups Password Protection – 2 levels User Programmable Logic Self Monitoring Circuit Breaker Trip and Maintenance Counter Trip Timers

# User Interface

20 Character x 4 Line Backlit LCD Menu Navigation Keys 9 User Programmable Tri-colour LEDs User Language Configuration

# **Monitoring Functions**

Primary/Secondary Current Phases and Earth Direction Primary/Secondary Line and Phase Voltages Apparent Power and Power Factor Real and Reactive Power W Hr & VAr Hr Forward and Reverse Historical Demand Record Positive Phase Sequence (PPS) Voltage & Current Negative Phase Sequence (NPS) Voltage & Current Zero Phase Sequence (ZPS) Voltage Frequency Direction Binary Input/Output status Trip circuit healthy/failure Time and date Starters Fault records Event records Energy Circuit breaker trip counters I<sup>2</sup>t summation for contact wear

# Hardware

1 CT 3 Binary Inputs 5 Binary Outputs
4 CT 3 Binary Inputs 5 Binary Outputs
4 CT 6 Binary Inputs 8 Binary Outputs
1 CT 3 VT 3 Binary Inputs 5 Binary Outputs
4 CT 3 VT 3 Binary Inputs 5 Binary Outputs
4 CT 3 VT 6 Binary Inputs 8 Binary Outputs



# Data Storage and Communication

Front USB port + Rear RS485 port Protocols - IEC60870-5-103, DNP3.0 or Modbus RTU Event Records – User Configurable Fault Records Waveform Records Measurands Commands Time Synchronism Viewing and Changing Settings

# Application

The Argus is a numerical overcurrent protection relay intended for use on distribution and industrial networks. It provides a highly comprehensive functional software package with a range of integral application functions aimed at reducing installation, wiring and engineering time. An extensive range of metered values can be viewed on the front LCD or at a remote point via the communication channel.

The integrated control feature allows operation of a single circuit breaker and monitoring of its trip and close circuits.

# **Function Matrix**

FUNCTION	FUNCTIONAL REQUIREMENT	7SR1101-1*A12-**A0	7SR1101-3*A12-**A0	7SR1102-1*A12-**A0	7SR1102-3*A12-**A0	7SR1204-2*A12-**A0	7SR1204-4*A12-**A0	7SR1205-2*A12-**A0	7SR1205-4*A12-**A0
27	Undervoltage					-		-	
37	Undercurrent				-			-	-
46BC	Broken Conductor / Load Unbalance				-			•	-
46NPS	Negative Phase Sequence Overcurrent				-			-	-
47	Negative Phase Sequence Voltage							-	-
49	Thermal Overload				-			-	-
50	Instantaneous Overcurrent			-	-			-	-
50G	Measured Instantaneous Earth Fault	-		-		-		-	
50SEF	Measured Instantaneous Sensitive Earth Fault		•		•				-
50N	Derived Instantaneous Earth Fault			-	-			-	
50BF	CB Failure	-	-	-	-	-	-	-	
51	Time Delayed Overcurrent			•	•			•	-
51G	Measured Time Delayed Earth Fault	-		-		-		-	
51SEF	Measured Time Delayed Sensitive Earth Fault		-		-		-		-
51N	Derived Time Delayed Earth Fault			-	-			-	-
59	Overvoltage					-	-	-	
59N	Neutral Voltage Displacement					-		-	
64H	High Impedance Restricted Earth Fault	-	-	-	-	-	-	-	-
67	Directional Overcurrent					-		-	-
67G	Directional Measured Earth Fault					-		-	
67SEF	Directional Sensitive Earth Fault					-	-		
67N	Directional Derived Earth Fault							-	-
81HBLS	Inrush Detector	-		-	-	-		-	
81	Under/Over Frequency					-	-	-	
	CONTROL / MONITOR								
51c	Cold Load - Phase Only			-	-			-	-
60CTS	CT Supervision								-
60VTS	VT Supervision								-
74T/CCS	Trip & Close Circuit Supervision		-	-	-			-	

Key - ■ - Included as standard □ - Ordering option



# **7SR11 Functional Diagrams**

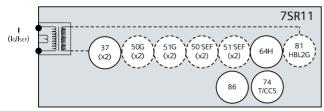


Fig 1. Single Pole Overcurrent Relay

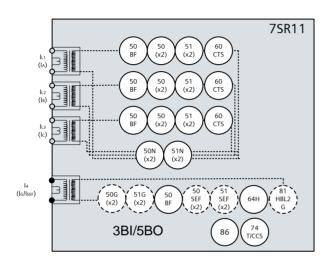
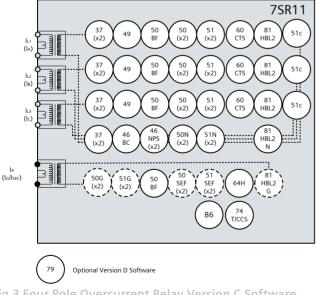


Fig 2. Four Pole Overcurrent Relay Version A software



### Fig 3 Four Pole Overcurrent Relay Version C Software

# **7SR12 Functional Diagrams**

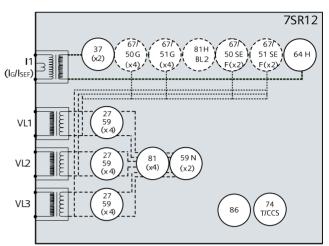


Fig 4. Single Pole Directional Relay

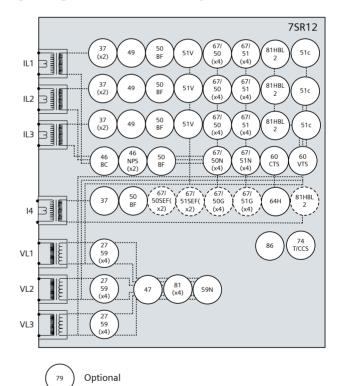


Fig 5. Four Pole Directional Overcurrent Relay

### Notes

- 1. Items shown dotted are only available in some models; please refer to the Ordering Information Section.
- 2. The use of some functions are mutually exclusive



# **Description of Functionality**

#### 27/59 Under/Over Voltage

Each element has settings for pickup level, drop-off level and Definite Time Lag (DTL) delays. Operates if voltage exceeds setting for duration of delay.

#### **37 Undercurrent**

Each element has settings for pickup level and Definite Time Lag (DTL) delays. Operates if current falls below setting for duration of delay.

#### 46BC Phase Unbalance/Broken Conductor

Element has settings for pickup level and DTL delay. With the circuit breaker closed, if the NPS:PPS current ratio is above setting this could be due to a broken conductor.

#### **46NPS Negative Phase Sequence Overcurrent**

Each element has user settings for pickup level and IDMTL or DTL delay, operates if NPS current exceeds setting and delay. NPS current elements can be used to detect unbalances on the system or remote earth faults when a delta-star transformer is in circuit.

#### 47 Negative Phase Sequence Voltage

Each element has settings for pickup level and Definite Time Lag (DTL) delays. Operates if NPS voltage exceeds setting for duration of delay.

#### **49 Thermal Overload**

The thermal algorithm calculates the thermal states from the measured currents and can be applied to lines, cables and transformers. Alarm outputs are given for thermal overload and thermal capacity.

#### 50BF Circuit Breaker Fail

The circuit breaker fail function may be triggered from an internal trip signal or from a binary input. Line currents and earth currents are monitored following a trip signal and an output is issued if any current is still detected, above setting, after a specified time interval. Alternatively, if the trip is from a mechanical protection the circuit breaker position can be used to determine a failure. A second time delay is available to enable another stage to be utilized if required. An input is also available to bypass the time delays when the circuit breaker is known to be faulty.

#### 51c Cold Load Pickup

If a circuit breaker is closed onto a 'cold' load, i.e. one that has not been powered for a prolonged period, this can impose a higher than normal load-current demand on the system which could exceed normal settings. These conditions can exist for an extended period and must not be interpreted as a fault. To allow optimum setting levels to be applied for normal operation, the cold load pickup feature will apply alternative current settings for a limited period. The feature resets when either the circuit breaker has been closed for a settable period, or if the current has reduced beneath a set level for a user set period.

#### 50/51 Phase Fault

50 INST/DTL and 51 IDMTL/DTL elements provide overcurrent protection, each with independent settings for pickup current, time-multiplier (51) and time-delays. User can select IEC or ANSI time current characteristics. The IDMT stage has a user programmable reset characteristic, either DTL or shaped current ~ time reset characteristic, to improve grading with electromechanical protection.

#### 50G/51G/50N/51N Earth Fault/Sensitive Earth Fault

Two earth fault measurement modes are available. One mode directly measures the earth current from an independent CT, or the residual connection of the 3 line CTs. This input can be ordered as either earth fault or sensitive earth fault (50G/51G).

The second mode derives the earth current internally from the 3 phase CT inputs to give earth fault (50N/51N). 50 INST/DTL and 51 IDMTL/DTL elements provide overcurrent protection, each with independent settings for pickup current, time-multiplier (51) and time-delays. User can select IEC or ANSI time current characteristics. The IDMT stage has a user programmable reset characteristic either DTL or shaped current ~ time reset characteristic to improve grading with electromechanical protection.

The directional SEF element is also suitable for use on compensated networks.

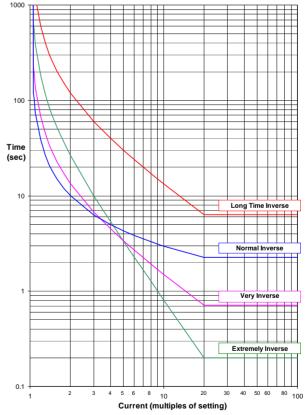


Fig 6. IEC Overcurrent Curves



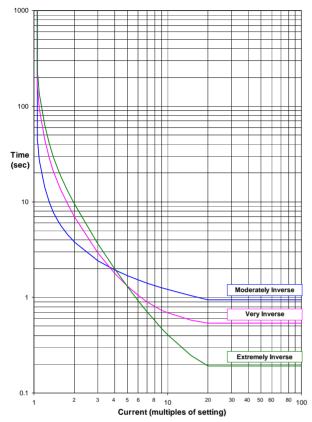


Fig 7. ANSI Overcurrent Curves

#### 51V Voltage Controlled Overcurrent

Each phase shaped overcurrent element can be independently controlled by the level of measured input voltage. For applied voltages above setting the 51-n element operates in accordance with its current setting but for voltages below the setting a multiplier is applied to reduce the 51-n pick up current setting.

#### 59N Neutral Overvoltage

Neutral overvoltage can be used to detect earth faults in high impedance earthed or isolated systems. Operates if the neutral voltage exceeds setting for duration of delay.

#### **60CTS CT Supervision**

The relay has two methods of CT supervision.. The 7SR11 monitors each phase current input and operates if any one or two inputs fall below the setting. The 7SR12 has the above method and an addition method that considers the presence of negative phase sequence current, without an equivalent level of negative phase sequence voltage, for a user set time as a CT failure.

Both element types have user operate and delay settings.

### **60VTS VT Supervision**

The VT supervision uses a combination of negative phase sequence voltage and negative phase sequence current to detect a VT fuse failure. This condition may be alarmed or used to inhibit voltage dependent functions. Element has user operate and delay settings.

### **64H Restricted Earth Fault**

The measured earth fault input may be used in a 64H high impedance restricted earth fault scheme to provide sensitive high speed unit protection. A calculation is required to determine the values of the external series stabilising resistor and non-linear shunt resistor which can be ordered separately.

### 67/67N Directional Control

Phase, earth and sensitive earth fault elements can be directionalised. Each element can be user set to Forward, Reverse, or Non-directional.

Directional Phase Fault elements are polarised from quadrature voltage.

Derived earth fault elements can be user set to be polarised from residual voltage or negative phase sequence voltage. Measured earth fault elements are polarized from Vo.

### 74T/CCS Trip & Close Circuit Supervision

The trip or close circuit(s) can be monitored via binary inputs. Trip circuit failure raises an HMI alarm and output(s).

#### 81HBL2 Inrush Restraint

Where second harmonic current is detected (i.e. during transformer energisation) user selectable elements can be blocked and an alarm given.

### 81 Under/Overfrequency

Each element has settings for pickup level, drop-off level and Definite Time Lag (DTL) delays. Operates if frequency exceeds setting for duration of delay. Typically applied in load shedding schemes.

### Standard Version – Plus 79 Auto-Reclose

A high proportion of faults on an overhead line network are transient and can be cleared quickly by high speed tripping followed by an automated circuit breaker reclose sequence.

The function provides independent phase fault and earth fault / sensitive earth fault sequences of up to 5 trip i.e. 4 reclose attempts before lockout. An auto-reclose sequence can be user set to be initiated from internal protection operation or via binary input from an external protection.

#### **Programmable Logic**

The user can map binary inputs, protection elements, LEDs and binary outputs together in a logical scheme. Up to 4 logic equations can be defined using standard logic functions e.g. Timers, AND/OR gates, Inverters and Counters to provide the user required functionality. Each logic equation output can be used for alarm & indication and/or tripping.

#### Virtual Inputs/Outputs

There are 8 virtual inputs/outputs to provide internal logical states to assist in the application of the functions. Each virtual I/O can be assigned in the same way as a physical I/O.

#### **Circuit Breaker Maintenance**

Two circuit breaker operations counters are provided to assist with maintenance scheduling. The maintenance counter records the overall number of operations and the



delta counter records the number of operations since the last reset.

An I<sup>2</sup>t summation counter provides a measure of the contact wear indicating the total energy interrupted by the circuit breaker contacts.

Each counter has a user set target operations count which, when reached, can be mapped to raise alarms/ binary outputs. A CB Trip Time meter is also available, which measures the time between the trip or open command being issued and the auxiliary contacts changing state.

# Control Mode

The relay has a control menu with access to commonly used command operations. Access to the control commands is restricted by a 4 character control function password. Each command requires a select then execute operation, if the execute operation is not performed within a time window the command is aborted. The following control functions are available:

CB Operation Auto Reclose In/Out Auto Reclose Trip & Reclose Auto Reclose Trip & Lockout SEF In/Out Inst Prot In/Out Hot Line Working In/Out



Fig 8. Example of Control Function View

# Data Acquisition -Via Communication Interface

### Sequence of event records

Up to 1000 events are stored and time tagged to 1ms resolution.

# Fault Records

The last 10 fault records are displayed on the relay fascia and are also available through the communication interface, with time and date of trip, measured quantities and type of fault.

# Waveform recorder

The waveform recorder stores analogue data for all poles and the states of protection functions, binary inputs, LEDs and binary outputs with user settable pre & post trigger data. A record can be triggered from protection function, binary input or via data communications. 10 records of 1 second duration are stored.

# Demand Metering

A rolling record of demand over the last 24h is stored. The demand is averaged over a user selectable period of time. A rolling record of such demand averages is stored and provides the demand history. A typical application is to record 15min averages for the last 7 days.

# Real Time Clock

The time and date can be set and are maintained while the relay is de-energised by a back up storage capacitor. The time can be synchronized from a binary input pulse or the data communication channel.

# Serial Communications

The relay offers a USB serial port as standard on the front of all units. All of the relays functions can be set on a PC using Reydisp Evolution via the USB port. The connection is made with a USB cable and operates with a 'plug and play' connection, so no pre-setting of the relay is required. The front port can be switched off or set to use either the DNP3.0, MODBUS-RTU, IEC60870-5-103 and ASCII protocols for testing purposes.

A rear RS485 electrical connection is available on all units for system interface connections. An internal terminating resistor is provided, which can be connected into the circuit by adding a wire loop between the relevant terminals.

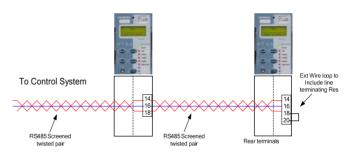


Fig 9. Typical RS485 connection

The rear RS485 can be user selected to be OFF, IEC60870-5-103, MODBUS RTU or DNP3.0 protocol.



# **Reydisp Evolution**

Reydisp Evolution is a Windows based software tool, providing the means for the user to apply settings, interrogate settings and retrieve events and disturbance waveforms from the device and is common to the entire range of Reyrolle protection relays.

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Time         Type         Action         Description         A           00:30:14.95%_GL/GL/2000         Overcurrent         Baised Settings changed         A           00:30:14.95%_GL/GL/2000         Overcurrent         Baised Setting changed         A           01:30:127:05.06.04/GL/2000         Overcurrent         Faised Setting Changed         A           01:30:26.058_GL/GL/2000         Overcurrent         Faised Setting Changed         A           01:30:26.058_GL/GL/2000         Overcurrent         Faised Setting Changed         A           01:39:26.058_GL/GL/2000         Overcurrent         Faised Setting Changed         A			and the second		
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01:37:59.500,81/01/2000 Overcurrenn Baised SetLing Gl selected 01:38:26.655,01/01/2000 Begyrolle Hodular II Baised Local & Semite 01:39:10.250,01/01/2000 Overcurrenn Baised SetLings changed	00:30:14.995,01/01/2000 Overcurre	nt Paised Settings char	nged.		
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Fig 10. Typical Reydisp Evolution Screenshot

#### Language Editor

The Language editor software gives the user the ability to customize the text displayed in the relays, Menu structure and instrumentation views. The tool allows a language file to be created and transferred to the relay also containing Western European characters.

ttings Text   Meters Text   Misc Text   Al	I Text Log	
	Alternate Setting Text	Icon Legend Image: Setting With Fixed Options Setting With Fixed Options Expand All Collapse A Setting Type: Setting Value Text: Original Alternate

Fig 11. Typical Language Editor Screenshot

# **Communications Editor**

To facilitate easier interfacing to a substation the relays default Protocol configuration may be modified using the communication editor software tool.

The communication editor is a PC based software package provided within the Reydisp software suite which allows modification of the IEC60870-5-103, DNP 3.0 and MODBUS Protocols.

nanj	Output Bin	ary Input   Analog	pue inquit	1			_					-	
	DNP3 #	CLASS		Static Ob/GVAR	Event Obi11.VAR	INVERT		CROB MASK		Enabled	Description	-	
	1	CLASS 2	0	2 .	2 .	False		PULSE ON	0	P	RL1	tircsosto	611
	2	CLASS 1		2 .		Falce		PULSE ON	0	P	RL2		
	3	CLASS 1		2 .		False		PULSE ON		P	RL3	E HOORAT	
	4	CLASS 1		2 💻	2 -	Falie		PULSE ON		Г	RL4		
	5	CLASS 1		2 .	2 .	False		PULSE ON		Г	RL5		
	6	CLASS 1				False	-	PULSE ON		Г	FIL 6		
	7	CLASS 1		2 .	2 .	False		PULSE ON		E	RL7		
	8	CLASS 1		2 .	2 .	False	٠	PULSE ON		E	FL.8		
	9	CLASS 1		2 👱		False		PULSE ON		E	RL9		
	10	CLASS 1		2 👱		False	-	PULSE ON		Г	RL10		
	11	CLASS 1		2 .		False		PULSE ON		Г	FIL.11		
	32	CLASS 1		2 💌	2 2	False	-	PULSE ON			RL12		
	12	CLASS 1		2 .	2 .	False	•	PULSE ON		Г	RL13		
	14	CLASS 1		2 .	2 💻	False		PULSE ON		Г	RL14		
	15	CLASS 1		2 .	2 .	False		PULSE ON		<b></b>	RL15		
	16	CLASS 1		2	2	False		PULSE ON			FL 16		
	17	CLASS 1			2 🔳	False	-	PULSE ON		Γ	RL 17		
	18	CLASS 1		2 .	2 .	False		PULSE ON		Г	FL.18		
	19	CLASS 1				False	-	PULSE ON			RL19		
	20	CLASS 1		2 .	2 .	False	-	PULSE ON		Г	FIL 20		
	21	CLASS 1		2 🚊		False		PULSE ON		Г	RL 21		
	22	CLASS 1				False	-	PULSE ON		E	RL 22	-	

Fig 12. Typical Communications Editor Screenshot



# Construction

The relay is housed in a 4U high size E4 case with a removable clear plastic fascia cover. The plastic fascia cover can be ordered with or without two push buttons. to allow the user to view the settings and instruments without removing the cover.

Two plastic handles are provided to allow the relay to be withdrawn from its case, contacts in the case ensure that the CT circuits and normally closed contacts remain short circuited when the relay is withdrawn.

The rear terminal blocks comprise M4 female terminals for ring crimp wire connections, to provide a secure and reliable termination.



Fig 13. Rear view of relay

# **User Interface**

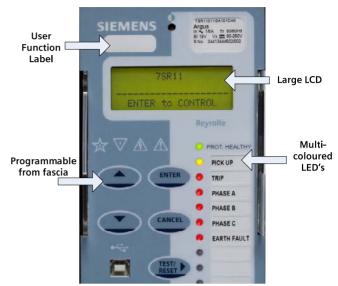


Fig 14. User Interface

The operator interface is designed to provide a user friendly method of controlling, viewing menus, entering settings and retrieving data from the relay. Five buttons are provided for navigation around the menu structure.

#### LCD

A 4 line by 20 character liquid crystal display with power save operation indicates the relay identifier, settings, instrumentation, fault data and control commands. Up to 6 user programmable general alarms can be configured to display your own indications on the LCD.

#### LEDs

A green steadily illuminated LED indicates the 'Protection Healthy' condition.

9 user programmable LEDs are available eliminating the need for expensive panel mounted pilot lights and associated wiring. Each LED is tri-color (red, green, yellow) allowing for clear indication of the associated function's state and has a label insert for identification.

### **Relay Information**

The device is identified by the rating label on the fascia. The user can also give the device its own identity by editing the 'Relay Identifier' displayed on the LCD or space is provided to place a slip in label giving the relays function.



# **Technical Data**

For full technical data refer to the Performance Specification Section of the Technical Manual.

# Inputs and Outputs

### **Current Inputs**

Quantity	3 x Phase & 1 x Earth or Sensitive Earth
Rated Current In	1/5A
Measuring Range	80 x ln
Instrumentation ≥ 0.1xIn	±1% ln
Frequency	50/60Hz
Thermal Withstand:	
Continuous	3 x ln
10 Minutes	3.5 x ln
2 Minutes	6 x ln
1 Second	100A (1A) 350A (5A)
1 Cycle	700A (1A) 2500A (5A)
Burden @ In	≤0.02VA (1A phase and Earth element) ≤0.2VA (5A phase and earth element)

### **Voltage Inputs**

Quantity	3 ph-ph
Nominal Voltage	40160V a.c. Range
Instrumentation ≥ 0.8xVn	±1% Vn
Thermal Withstand:	
Continuous	270V
1 Second	
Burden @ 110V	≤ 0.06 VA

# **Auxiliary Supply**

Rated DC Voltage	110/125/22 Range 64 tr 24/48/60V Range 18 tr	o 300V
Allowable superimposed ac component	12% of DC	voltage
Rated AC Voltage	115 VAC 50 Range 92 t 47-52/57-6	o 138 V rms AC
Power Consumption:	Min (DC) Max (DC) Min (AC) Max (AC)	
Allowable breaks/dips in	DC	50ms
supply (collapse to zero)	AC	2.5/3 cycles @50/60Hz

### **Binary Inputs**

Number	3 or 6			
Operating Voltage	19V dc	DC Range 17 to 320V dc AC Range 92 to 138 VRMSAC		
	88V dc	Range 70 to 320V dc		
Maximum dc current for operation	1.5mA			
Maximum peak ac current for operation	1.5mA			
Pick Up Delay	User Selectable 0 to 14,400,000ms (up to 4 hours)			
Drop Off Delay	User Selectable 0 to 14,400,000ms (up to 4 hours)			
For AC operation the	Dinicku	n dalay should be set to Oms		

For AC operation the BI pick-up delay should be set to 0ms and the drop-off delay to 20ms.

#### **Binary Outputs**

Number	5 or 8
	(3 change over contacts)
Operating Voltage	Voltage Free
Operating Mode	User selectable - Self or Hand/Electrical Reset or pulsed.
Operating Time from	<20ms
Energizing Binary Input	<20115
Making Capacity:	
Carry continuously	5A ac or dc
Make and carry	20A ac or dc for 0.5s
(L/R $\leq$ 40 ms and V $\leq$ 300	30A ac or dc for 0.2s
V)	
Breaking Capacity	
$(\leq 5 \text{ A and } \leq 300 \text{ V})$ :	
AC Resistive	1250 VA
AC Inductive	250 VA at p.f. ≤ 0.4
DC Resistive	75 W
DC Inductive	30 W at $L/R \le 40$ ms
	50 W at $L/R \le 10$ ms

# Unit Design

Housing	E4 (see dimension drawing)
Indication	20 Character 4 line Display Relay Healthy LED 9 Tri Coloured User Programmable Self or Hand Reset LED's
With-drawable Element	Yes
User Interface	5 Navigation Keys
Weight	Typical 3.1Kg
IP Rating Installed with cover	IP 50



# Serial Interface

**Communication Port** 

Protocols

Front USB Type B Rear RS485 2 wire electrical IEC60870-5-103 MODBUS RTU DNP3.0

# Data Storage

Fault Record	10
Waveform Record	10 x 1sec 2 x 5sec 5 x 2sec 1 x 10sec Pre trigger 1090%
Events	1000 1ms Resolution

# **Mechanical Tests**

# Vibration (Sinusoidal)

IEC 60255-21-1 Class I

Туре	Level	Variation
Vibration response	0.5 gn	$\leq$ 5 %
Vibration response	1.0 gn	≤ 5 %

# Shock and Bump

IEC 60255-21-2 Class I

Туре	Level	Variation
Shock response	5 gn, 11 ms	$\leq$ 5 %
Shock withstand	15 gn, 11 ms	≤ 5 %
Bump test	10 gn, 16 ms	≤ 5 %

### Seismic

IEC 60255-21-3 Class I

Туре	Level	Variation
Seismic response	X-plane - 3.5mm displacement below crossover freq (8-9Hz) 1gn and above Y-plane – 1.5mm displacement below crossover freq (8-9Hz) 0.5gn above	≤ 5 %

# **Mechanical Classification**

Durability

>10<sup>6</sup> operations

# **Electrical Tests**

Insulation

IEC 60255-5

Туре	Level
Between any terminal and earth	2.0 kV AC RMS for 1 min
Between independent circuits	2.0 kV AC RMS for 1 min
Across normally open contacts	1.0 kV AC RMS for 1 min

# High Frequency Disturbance

IEC 60255-22-1 Class III

Туре	Level	Variation
Common	2.5 kV	$\leq$ 5 %
(longitudinal) mode		
Series (transverse)	1.0 kV	$\leq$ 5 %
mode		

# **Electrostatic Discharge**

IEC 60255-22-2 Class IV

Туре	Level	Variation
Contact discharge	8.0 kV	$\leq$ 5 %

### **Fast Transients**

IEC 60255-22-4 Class A (2002)

Туре	Level	Variation
5/50 ns 2.5 kHz	4kV	≤ 5 %
repetitive		

# Surge Immunity

IEC 60255-22-5

Туре	Level	Variation
Between all terminals and earth	4.0 kV	≤ 10 %
Between any two independent circuits	2.0kV	≤ 10 % <b>*</b>

\*Note 45ms pick up delay for DTL applied to binary inputs.

### **Conducted Radio Frequency Interference**

IEC 60255-22-6

Туре	Level	Variation
0.15 to 80 MHz	10 V	$\leq$ 5 %



# Radiated Radio Frequency

# IEC 60255-25

Туре	Limits at 10 m, Quasi-peak
30 to 230 MHz	40 dB(μV)
230 to 10000 MHz	47 dB(μV)

### Conducted Radio Frequency

Туре	Limits	
	Quasi-peak	Average
0.15 to 0.5 MHz	79 dB(μV)	66 dB(μV)
0.5 to 30 MHz	73 dB(μV)	60 dB(µV)

### **Radiated Immunity**

IEC 60255-22-3 Class III

Туре	Level
80 MHz to 1000 MHz Sweep	10 V/m
1.4GHz to 2.7GHz Sweep	10V/m
80,160,380,450,900,1850,2150 MHz Spot	10V/m

# **Climatic Tests**

# Performance

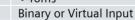
# 27/59 Under/Over Voltage

Number of Elements	4 Under or Over
Operate	Any phase or All phases
Voltage Guard	1,1.5200V
Setting Range Vs	5,5.5200V
Hysteresis Setting	0.0.180%
Vs Operate Level	100% Vs, ±1% or ±0.25V
Reset Level:	
Overvoltage	=(100%-hyst)xVop, ±1%
Undervoltage	=(100%+hyst)xVop, ±1%
Delay Setting td	0.00,0.0120,20.5100,101 1000,101010000,10100144 00s
Basic Operate Time :	
0 to 1.1xVs	73ms ±10ms
0 to 2.0xVs	63ms ±10ms
1.1 to 0.5xVs	58ms ±10ms
Operate time following delay.	Tbasic +td , ±1% or ±10ms
Inhibited by	Binary or Virtual Input VT Supervision Voltage Guard

### 37 Undercurrent

_		Number of Elements	2 Phase and 2 EF
Temperature		Operate	Any phase or ALL
IEC 60068-2-1/2		Setting Range Is	0.05,0.105.0 x In
		Operate Level	100% ls, ±5% or ±1%xln
Operating Range	-10 °C to +55 °C	Current Guard	Phase 0.05,0.15.0 x In
Storage range Humidity	-25 °C to +70 °C	Delay Setting td	0.00,0.0120,20.5100,101 1000,101010000,10100144 00s
IEC 60068-2-78		Basic Operate Time: 1.1 to 0.5xln	35ms ±10ms
Operational test	56 days at 40 °C and 93 % relative humidity	Operate time following delay.	Tbasic +td , $\pm$ 1% or $\pm$ 10ms
	,	Overshoot Time	< 40ms

Inhibited by





# 46 Negative Phase Sequence Overcurrent

Number of Elements	DT & IT
DT Setting Range Is	0.05,0.104.0 x In
DT Operate Level	100% ls, ±5% or ±1%xln
DT Delay Setting td	0.00,0.0120,20.5100,101 1000,101010000,10100144 00s
DT Basic Operate Time	
0 to 2 xls	40ms ±10ms
0 to 5 xls	30ms ±10ms
DT Operate time	Tbasic +td , $\pm$ 1% or $\pm$ 10ms
following delay.	
IT Char Setting	IEC NI,VI,EI,LTI ANSI MI,VI,EI & DTL
IT Setting Range	0.052.5
Tm Time Multiplier	0.025,0.0501.6
Char Operate Level	105% ls, ±4% or ±1%ln
Overshoot Time	< 40ms
Inhibited by	Binary or Virtual Input

### 47 Negative Phase Sequence

2
1,1.590V
0,0.180%
100% Vs, ±2% or ±0.5V
0.00,0.0120,20.5100,101 1000,101010000,10100144 00s
80ms ±20ms
55ms ±20ms
Tbasic +td , ±2% or ±20ms
< 40ms
Binary or Virtual Input

# 49 Thermal Overload

Operate levels	Operate and Alarm
Setting Range Is	0.10,0.113.0 x In
Operate Level	100% ls, ±5% or ±1%xln
Time Constant Setting	1,1.51000min
Operate time	$t = \tau \times In \left\{ \frac{I^2 \cdot I_p^2}{I^2 \cdot (k \times I_B)^2} \right\}$
	±5% absolute or ±100ms where
	lp = prior current
Alarm Level	Disabled, 50,51100%
Inhibited by	Binary or Virtual Input

# 50 (67) Instantaneous & DTL OC&EF (Directional)

Operation – 7SR12 only	Non directional, Forward or reverse
Elements	Phase, Derived Earth, Measured Earth & SEF
Number of Elements 2 x 7SR11 4 x 7SR12	2/4 x OC 2/4 x Derived EF 'N' 2/4 x Measured EF 'G' where fitted 2/4 x SEF where fitted
Setting Range Is	0.05,0.0650 x ln SEF 0.0055 x ln
Time Delay	0.0014400s
Operate Level	100% ls, ±5% or ±1%xln
Operate time: 50	0 to 2xls – 35ms, ±10ms, 0 to 5xls – 25ms, ±10ms
50N	0 to 2xls – 40ms, ±10ms, 0 to 5xls – 30ms, ±10ms
Operate time following delay	Tbasic +td , ±1% or ±10ms
Inhibited by	Binary or Virtual Input Inrush detector VT Supervision

# 51(67) Time Delayed OC&EF (Directional)

Operation – 7SR12 onlyNon directional, Forward or reverseElementsPhase, Derived Earth, Measured Earth & SEFNumber of Elements $2/4 \times OC$ $2 \times 7SR11$ $2/4 \times DC$ $4 \times 7SR12$ $2/4 \times Derived EF 'N'$ $4 \times 7SR12$ $2/4 \times Measured EF 'G'$ $2/4 \times SEF where fittedCharacteristicIEC NI,VI,EI,LTI ANSI MI,VI,EI &DTLSetting Range Is0.05, 0.062.5 \times InSEF 0.0050.5 \times InTime Multiplier0.025, 0.051.6Time Delay0, 0.0120sOperate Level105\% Is, \pm 4\% or \pm 1\%xInMinimum Operate timeIECt_{op} = \frac{K}{\left[\frac{L}{L_1}\right]^{a'} - 1} \times TmANSI\frac{1}{t_{op}} = \left[\frac{A}{\left[\frac{L}{L_1}\right]^{a'} - 1} + B\right] \times TmFollower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual InputInrush detectorVT Supervision$			
InitialInitialEarth & SEFNumber of Elements $2 \times 7SR11$ $4 \times 7SR12$ $2/4 \times Derived EF 'N'$ $4 \times 7SR12$ $2/4 \times Measured EF 'G'$ $2/4 \times SEF$ where fittedCharacteristicIEC NI,VI,EI,LTI ANSI MI,VI,EI & DTLSetting Range Is $0.05, 0.062.5 \times In$ Setting Range Is $0.025, 0.051.6$ Time Multiplier $0.025, 0.051.6$ Time Delay $0, 0.0120s$ Operate Level $105\%$ Is, $\pm 4\%$ or $\pm 1\%$ InMinimum Operate timeIEC $t_{op} = \frac{K}{\left[\frac{L}{L_1}\right]^n - 1} \times Tm$ ANSI $t_{op} = \left[\frac{A}{\left[\frac{L}{L_1}\right]^n - 1} + B\right] \times Tm$ $\pm 5 \%$ absolute or $\pm 30$ msFollower Delay $0 - 20s$ ResetANSI decaying, $0 - 60s$ Inhibited byBinary or Virtual Input Inrush detector	Operation – 7SR12 only	,	
2 x 7SR112/4 x Derived EF 'N'4 x 7SR122/4 x Measured EF 'G' 2/4 x SEF where fittedCharacteristicIEC NI,VI,EI,LTI ANSI MI,VI,EI & DTLSetting Range Is0.05,0.062.5 x In SEF 0.0050.5 x InTime Multiplier0.025,0.051.6Time Delay0,0.01 20sOperate Level105% Is, ±4% or ±1%xInMinimum Operate time IEC $t_{op} = \frac{K}{\left[\frac{f}{f_{a}}\right]^{a} - 1} \times Tm$ ANSI $t_{op} = \left[\frac{A}{\left[\frac{f}{f_{a}}\right]^{a} - 1} + B\right] \times Tm$ Follower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector	Elements		
4 x 7SR122/4 x Measured EF 'G' 2/4 x SEF where fittedCharacteristicIEC NI,VI,EI,LTI ANSI MI,VI,EI & DTLSetting Range Is0.05,0.062.5 x In SEF 0.0050.5 x InTime Multiplier0.025,0.051.6Time Delay0,0.01 20sOperate Level105% Is, ±4% or ±1%xInMinimum Operate time IEC $t_{op} = \frac{K}{\left[\frac{f}{f_{a}}\right]^{a} - 1} \times Tm$ ANSI $t_{op} = \left[\frac{A}{\left[\frac{f}{f_{a}}\right]^{a} - 1} + B\right] \times Tm$ Follower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector	Number of Elements	2/4 x OC	
In Fourier2/4 x SEF where fitted2/4 x SEF where fittedCharacteristicIEC NI,VI,EI,LTI ANSI MI,VI,EI & DTLSetting Range Is0.05,0.062.5 x In SEF 0.0050.5 x InTime Multiplier0.025,0.051.6Time Delay0,0.01 20sOperate Level105% Is, ±4% or ±1%xInMinimum Operate time IEC $t_{op} = \frac{K}{\left[\frac{f}{f_{a}}\right]^{\alpha} - 1} \times Tm$ ANSI $t_{op} = \left[\frac{A}{\left[\frac{f}{f_{a}}\right]^{-1} + B}\right] \times Tm$ ± 5 % absolute or ± 30 msFollower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector	2 x 7SR11	2/4 x Derived EF 'N'	
CharacteristicIEC NI, VI, EI, LTI ANSI MI, VI, EI & DTLSetting Range Is0.05, 0.062.5 x In SEF 0.0050.5 x InTime Multiplier0.025, 0.051.6Time Delay0, 0.01 20sOperate Level105% Is, ±4% or ±1%xInMinimum Operate time IEC $t_{op} = \frac{K}{\left[\frac{f}{L_0}\right]^{\alpha} - 1} \times Tm$ ANSI $t_{op} = \left[\frac{A}{\left[\frac{f}{L_0}\right]^{\alpha} - 1} + B\right] \times Tm$ ± 5 % absolute or ± 30 msFollower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector	4 x 7SR12	2/4 x Measured EF 'G'	
InterventionDTLSetting Range Is0.05,0.062.5 x In SEF 0.0050.5 x InTime Multiplier0.025,0.051.6Time Delay0,0.01 20sOperate Level105% Is, ±4% or ±1%xInMinimum Operate time IEC $t_{op} = \frac{K}{\left[\frac{L}{L_s}\right]^{ar} - 1} \times Tm$ ANSI $t_{op} = \left[\frac{K}{\left[\frac{L}{L_s}\right]^{ar} - 1} + B\right] \times Tm$ ± 5 % absolute or ± 30 msFollower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector		2/4 x SEF where fitted	
Setting Range Is0.05,0.062.5 x In SEF 0.0050.5 x InTime Multiplier0.025,0.051.6Time Delay0,0.01 20sOperate Level105% Is, ±4% or ±1%xInMinimum Operate time IEC $t_{op} = \frac{K}{\left[\frac{L}{L_s}\right]^{a} - 1} \times Tm$ ANSI $t_{op} = \left[\frac{A}{\left[\frac{L}{L_s}\right]^{a} - 1} + B\right] \times Tm$ ± 5 % absolute or ± 30 msFollower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector	Characteristic	IEC NI, VI, EI, LTI ANSI MI, VI, EI &	
SEF 0.0050.5 x InTime Multiplier0.025,0.051.6Time Delay0,0.01 20sOperate Level105% ls, ±4% or ±1%xlnMinimum Operate timeIECIEC $t_{op} = \frac{K}{\left[\frac{L}{L_{o}}\right]^{a}-1} \times Tm$ ANSI $t_{op} = \left[\frac{A}{\left[\frac{L}{L_{o}}\right]^{a}-1} + B\right] \times Tm$ ± 5 % absolute or ± 30 msFollower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector		DTL	
Time Multiplier0.025,0.051.6Time Delay0,0.01 20sOperate Level105% ls, ±4% or ±1%xlnMinimum Operate time $t_{op} = \frac{K}{\left[\frac{L}{L_o}\right]^a - 1} \times Tm$ ANSI $t_{op} = \left[\frac{A}{\left[\frac{L}{L_o}\right]^a - 1} + B\right] \times Tm$ É 5 % absolute or ± 30 ms0 - 20sFollower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector	Setting Range Is		
Time Delay $0, 0.0120s$ Operate Level $105\%$ Is, $\pm 4\%$ or $\pm 1\%x$ InMinimum Operate time $t_{op} = \frac{K}{\left[\frac{I}{L_{o}}\right]^{\alpha} - 1} \times Tm$ ANSI $t_{op} = \left[\frac{A}{\left[\frac{L}{L_{o}}\right]^{\alpha} - 1} + B\right] \times Tm$ $\pm 5\%$ absolute or $\pm 30$ msFollower Delay $0 - 20s$ ResetANSI decaying, $0 - 60s$ Inhibited byBinary or Virtual Input Inrush detector			
Operate Level105% ls, ±4% or ±1%xlnMinimum Operate time105% ls, ±4% or ±1%xlnIEC $t_{op} = \frac{K}{\left[\frac{L}{L_{o}}\right]^{a} - 1} \times Tm$ ANSI $t_{op} = \left[\frac{A}{\left[\frac{L}{L_{op}}\right]^{a} - 1} + B\right] \times Tm$ ± 5 % absolute or ± 30 msFollower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector	Time Multiplier	0.025,0.051.6	
Minimum Operate time IEC $t_{op} = \frac{K}{\left[\frac{f}{L_{0}}\right]^{a} - 1} \times Tm$ ANSI $t_{op} = \left[\frac{A}{\left[\frac{f}{L_{0}}\right]^{a} - 1} + B\right] \times Tm$ $\pm 5$ % absolute or $\pm 30$ msFollower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector	Time Delay	0,0.01 20s	
IEC $t_{op} = \frac{K}{\left[\frac{I}{LS}\right]^{\alpha} - 1} \times Tm$ ANSI $t_{op} = \left[\frac{A}{\left[\frac{I}{LS}\right]^{p} - 1} + B\right] \times Tm$ $\pm 5$ % absolute or $\pm 30$ msFollower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector	Operate Level	105% ls, ±4% or ±1%xln	
Interm $t_{op} = \frac{1}{\left[\frac{I}{L}\right]^{d} - 1} \times Im$ ANSI $t_{op} = \left[\frac{A}{\left[\frac{I}{L}\right]^{p} - 1} + B\right] \times Tm$ $\pm 5$ % absolute or $\pm 30$ msFollower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector	Minimum Operate time		
ANSI $t_{op} = \begin{bmatrix} A \\ f_{p}^T - 1 \end{bmatrix} \times Tm$ $\pm 5$ % absolute or $\pm 30$ msFollower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector	IEC	$t = \frac{K}{1} \times Tm$	
± 5 % absolute or ± 30 ms       Follower Delay     0 - 20s       Reset     ANSI decaying, 0 - 60s       Inhibited by     Binary or Virtual Input Inrush detector		L13 J	
± 5 % absolute or ± 30 ms       Follower Delay     0 - 20s       Reset     ANSI decaying, 0 - 60s       Inhibited by     Binary or Virtual Input Inrush detector	ANSI	$t = \left[ \frac{A}{A} + B \right] \times Tm$	
Follower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector		$L_{op} = \left\lfloor \left\lfloor \underline{L}_{s} \right\rfloor^{p} - 1 + D \right\rfloor^{1}$	
Follower Delay0 - 20sResetANSI decaying, 0 - 60sInhibited byBinary or Virtual Input Inrush detector			
ResetANSI decaying, 0 – 60sInhibited byBinary or Virtual InputInrush detector			
Inhibited by Binary or Virtual Input Inrush detector		0 200	
Inrush detector			
	Inhibited by		
VI Supervision			
		VI Supervision	



# 51V Voltage Controlled Overcurrent

Setting Range	5,5.5200V
Setting hange	5,5.52000
Operate Level	100% Vs, ±5% or ±1%xVn
Multiplier	0.25.0.31 x 51ls
Inhibited by	VT Supervision

### 50BF Circuit Breaker Fail

Operation	Current check - Phase and Measured Earth with independent settings Mechanical Trip CB Faulty Monitor
Setting Range Is	0.05,0.0552.0 x In
2 Stage Time Delays	Timer 1 2060000ms Timer 2 2060000ms
Operate Level	100% ls, ±5% or ±1%xln
Disengaging time	< 20ms
Operate time following delay	Tcbf ±1% or ±2ms
Triggered by	Any function mapped as trip contact.
Inhibited by	Binary/Virtual Input
Timer By pass	Yes, 50BF CB Faulty Input

# 59N Neutral Voltage Displacement

Number of Elements	DT & IT
DT Setting Range Is	1100V
DT Operate Level	100% Vs, ±2% or ±0.5V
DT Delay Setting td	014400s
DT Basic Operate Time	
0V to 1.5 x Vs	76ms ±20ms
0V to 10 x Vs	63ms ±20ms
DT Operate time	Tbasic +td , ±1% or ±20ms
following delay.	
IT Char Setting	IDMTL & DTL
IT Setting Range	1100V
Tm Time	0.1140
Multiplier(IDMT)	
Delay (DTL)	020s
Reset	ANSI Decaying, 060s
Char Operate Level	105% Vs, ±2% or ±0.5V
Inhibited by	Binary or Virtual Input

### 60 Supervision

СТ	7SR11 Current 7SR12 Current or Vnps & Inps
VT	nps/zps

# 64H Restricted Earth Fault

Setting Range	SEF input	0.005, 0.006 0.100, 0.105 0.950 xIn
	EF input	0.05, 0.055 0.95 xln
Operate Level	100% ls, ±5% or ±1%xln	
Time Delay	0.00 14400s	
Basic Operate Time	0 to 2 xls 45ms ±10ms	
	0 to 5 xls 35ms ±10ms	
Inhibited by	Binary or Virtual Input	

# 74T/CC Trip/Close Circuit Supervision

Number of supervisable circuits	3 x Trip and 3 x Close
Number of BI's Required	1 or 2 per function

#### 79 AutoReclose

Operating Mode	Phase, Earth, SEF External
Number of Reclosures	4
Number of Trips	5
Dead Time	014400
Reclaim Time	0600
Lockout Reset	CB, Timer & Bl

### 81 Under/Over Frequency

Number of Elements	4 Under or Over
Under Voltage Guard	Yes/No
Setting Range Hz	43,43.0168Hz
Hysteresis Setting	0, 0.1 2%
Operate Level	100% Fs ±10mHz
Operate Time	Typical <150ms
Vs Operate Delay	014400s

#### **Control Functions**

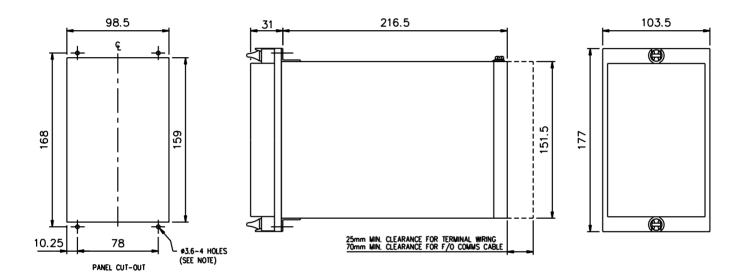
CB	Open/Close
Inst Prot	IN/OUT
EF	IN/OUT
SEF	IN/OUT
Hot Line	IN/OUT
Relay Mode	Local/Remote/Local or Remote
Reset	LED's & O/P's

#### **CB** Maintenance

Trip Counter	Total & Delta 010000
Counts to AR Block	010000
Frequent Operations	010000
I <sup>2</sup> t Alarm	10100000



# **Case Dimensions**



NOTE: THE Ø3.6 HOLES ARE FOR M4 THREAD FORMING (TRILOBULAR) SCREWS. THESE ARE SUPPLIED AS STANDARD AND ARE SUITABLE FOR USE IN FERROUS/ALUMINUM PANELS 1.6mm THICK AND ABOVE. FOR OTHER PANELS, HOLES TO BE M4 CLEARANCE (TYPICALLY Ø4.5) AND RELAYS MOUNTED USING M4 MACHINE SCREWS, NUTS AND LOCKWASHERS (SUPPLIED IN PANEL FIXING KIT).

Fig 15. E4 Case Dimensions



# 7SR11 Connection Diagram

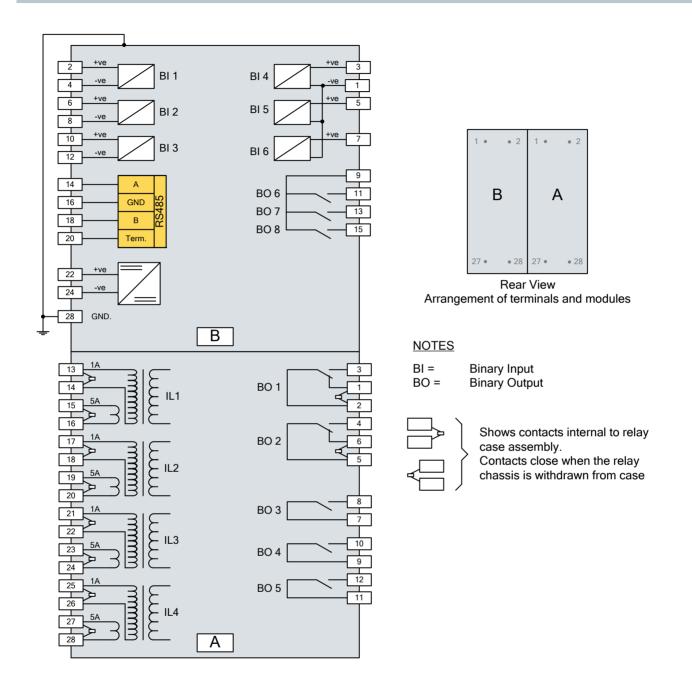


Fig16. Diagram showing 7SR11 relay with 4 CT inputs, 6 binary inputs and 8 binary outputs.



# 7SR12 Connection Diagram

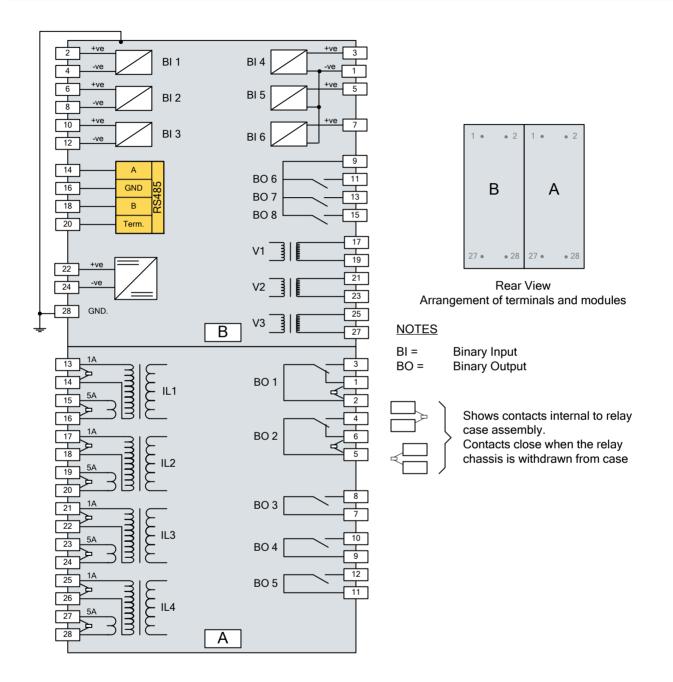


Fig17. Diagram showing 7SR12 relay with 4 CT inputs, 3 VT inputs, 6 binary inputs and 8 binary outputs.



# Ordering Information – 7SR11 Argus Non-Directional Overcurrent

	1       2       3       4       5       6       7       8       9         ORDER-No.:       7       S       R       1       1       0       -       -	9 10 11 12 13 14 A 1 2 -	15 16 A 0
			<u> </u>
	n Product Family 5       nt - Non Directional 1		
overediterit			1 1
Relay Type	6     0		
Case, I/O an			!!
	CT, 3 Binary Inputs / 5 Binary Outputs, 10 LEDs         1           CT, 3 Binary Inputs / 5 Binary Outputs, 10 LEDs         2	<b>C</b>         A/C/D	
	CT, 6 Binary Inputs / 8 Binary Outputs, 10 LEDs 3	C/D	i i
Measuring in	a input 8		
1/5 A, 50/60H		A/C/D	1 1
1/5 A, 50/60Hz	0Hz with SEF Input <sup>2</sup> 3	C/D	!!
Auxiliary vol	voltage	9	
80-250V DC /	C / 115V AC <sup>6</sup> , binary input threshold 19V DC	siii ii	i i
24-00V DC, DI	binary input threshold 19V DC		
Spare		10	i i
Communica	cation Interface	11	1 1
	version - included in all models, USB front port, RS485 rear port	1	i i
Protocol		12	
	0-5-103, Modbus RTU and DNP3(user selectable setting)	2	1 1
Front Course	_		!!
Front Cover Standard Versi	ersion - No Push Buttons	13	
	ns - Down and right Arrows	2	i i
Protection F	n Function Packages	14	
Basic version 5		A	!!
46BC 50	Broken conductor/load unbalance Instantaneous phase fault overcurrent		
50BF	Circuit breaker fail		i i
50G/50N	Instantaneous earth fault		
51 51G/51N	Time delayed phase fault overcurrent Time delayed earth fault		
60CTS	CT Supervision		
64H	High impedance REF		i i
74T&C For future de	Trip & Close circuit supervision	В	! !
Standard versi		C	
37	Undercurrent		i i
46BC <sup>3)</sup>	Broken conductor/load unbalance		
46NPS <sup>3)</sup> 49 <sup>3)</sup>	Negative phase sequence overcurrent Thermal overload		
50 <sup>3)</sup>	Instantaneous phase fault overcurrent		i i
50BF 3)	Circuit breaker fail		1
50G/50N 50 SEF <sup>2)</sup>	Instantaneous earth fault Instantaneous Sensitive Earth Fault		
50 3EF	Time delayed phase fault overcurrent		1
51G/51N	Time delayed earth fault		i i
51 SEF <sup>2)</sup>	Time Delayed Sensitive Earth Fault		!!
60CTS <sup>3)</sup> 64H	CT Supervision High impedance REF		
74T&C	Trip & Close circuit supervision		
51c <sup>3)</sup>	Cold load pickup		ļļ
81HBL2 <sup>4)</sup>	Inrush Restraint Programmable Logic		
Standard ver		D	
79	Autoreclose		
Additional F	I Functionality		 15
	nal functionality		A
Spare			 16
<u> puio</u>			0

<sup>1)</sup> 4CT is configured as 3PF + EF

<sup>2)</sup> 4CT is configured as 3PF + SEF/REF (user selectable setting).

<sup>3)</sup> Functions only available in 4CT relay

4) Not available on single-pole SEF variant

<sup>5)</sup> Protection function package ordering option A is only available on hardware variant 7SR1102-1XA12-XAA0 - 4CT 3BI 5BO

<sup>6)</sup> 115V AC supported by devices with hardware version CC or later



# Ordering Information – 7SR12 Argus Directional Overcurrent

	ORDER-No.:	1 2 3 4 5 6 7 7 S R 1 2 0	8 9 10 11 12 - A 1 2	13 14 15 16 - A O
Protection Proc Overcurrent - Di		<u> </u>		
Overcurient - Di				
Relay Type		6		
Case, I/O and F	Fascia	7		
E4 case, 1 CT, 3	VT, 3 Binary Inputs / 5 Binary Outputs, 10 LEDs	4		i ċ i i
	VT, 3 Binary Inputs / 5 Binary Outputs, 10 LEDs	5		
E4 case, 4 CT, 3	VT, 6 Binary Inputs / 8 Binary Outputs, 10 LEDs	6		
Measuring inpu	ut		8	
1/5 A, 63.5/110\			2	
<u>1/5 A, 63.5/110V,</u>	50/60Hz with SEF Input <sup>2)</sup>			
Auxiliary voltage			9	iiii
	5V AC <sup>5)</sup> , binary input threshold 19V DC		G	
	rry input threshold 88V DC y input threshold 19V DC			
				i i i i
Spare			10	
Communication	n Interface		11	
Standard version	n - included in all models, USB front port, RS485 rear port		1	
Drotocol				
Protocol IEC 60870-5-10	3, Modbus RTU and DNP3 (user selectable setting)		12	
	.,		· · · · ·	i i i i
Front Cover				13
	- No Push Buttons			
	ction Packages			14
For future devel				A     B
For future develo	- included in all models			
27/59	Under/Over Voltage			
37	Undercurrent			l i i
46BC 3)	Broken conductor/load unbalance			
46NPS 3)	Negative phase sequence overcurrent			
47 <sup>3)</sup> 49 <sup>3)</sup>	Negative phase sequence voltage Thermal overload			
50BF <sup>3)</sup>	Circuit breaker fail			
51V <sup>3)</sup>	Voltage Controlled Overcurrent			
59N	Neutral voltage displacement			
60CTS <sup>3)</sup>	CT Supervision			
60VTS <sup>3)</sup>	VT Supervision			
64H	High impedance REF			
67/50 <sup>3)</sup>	Directional instantaneous phase fault overcurrent			
67/50G 67/50N	Directional instantaneous earth fault			
67/50 SEF <sup>2)</sup>	Directional instantaneous Sensitive Earth Fault			
67/51 <sup>3)</sup>	Directional time delayed phase fault overcurrent			
67/51G 67/51N 67/51 SEF <sup>2)</sup>	Directional time delayed earth fault Directional time delayed Sensitive Earth Fault			
74T&C	Trip & Close circuit supervision			
51c <sup>3)</sup>	Cold load pickup			
81HBL2 <sup>4)</sup>	Inrush Restraint			
81U/O	Under/Over Frequency			i i
<u></u>	Programmable logic			
Standard version	n - plus Autoreclose			D
79				
Additional Fun				
No additional fue				15
	ctionality nctionality			15   A
Spare				

<sup>3)</sup> Functions only available in 4CT relay

<sup>4)</sup> Not available on single-pole SEF variant

<sup>5)</sup> 115V AC supported by devices with hardware version CC or later



 $<sup>^{\</sup>rm 1)}4\rm CT$  is configured as 3PF + EF

<sup>&</sup>lt;sup>2)</sup> 4CT is configured as 3PF + SEF/REF (user selectable setting)

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